

PHYS 320 ANALYTICAL MECHANICS

Dr. Gregory W. Clark
Fall 2018.

The Simple Harmonic Oscillator

- Differential equation:

$$m \frac{d^2 x}{dt^2} + kx = 0 \qquad \omega_o \equiv \sqrt{\frac{k}{m}} = \text{natural frequency}$$

- Solutions:

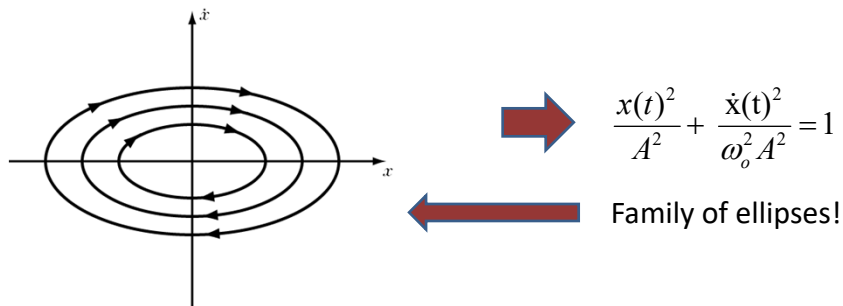
$$x(t) = C_1 e^{+i\omega_o t} + C_2 e^{-i\omega_o t} = B_1 \cos(\omega_o t) + B_2 \sin(\omega_o t) = A \cos(\omega_o t - \delta)$$

Phase plots

- For a 1-D oscillator, the motion is completely specified by two quantities: $x(t)$ and $\dot{x}(t)$

- Note that $E_{mech} = K + U = \frac{1}{2} m \dot{x}^2 + \frac{1}{2} k x^2$

$$= \frac{1}{2} m (-A\omega_o \sin(\omega_o t - \phi))^2 + \frac{1}{2} k (A \cos(\omega_o t - \phi))^2$$

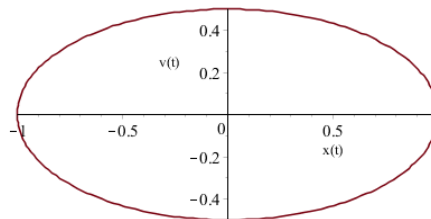


Phase plots with MAPLE

```

> restart;
> with(plots):
> x:=A*cos(omega*t+phi);
> v:=diff(x,t);
> phi:=0;A:=1;omega:=1/2;
> plot([x,v,t=0..4*Pi],labels=["x(t)", "v(t)"],scaling=constrained);

```



Damped Oscillations (linear damping)

$$m \frac{d^2 x}{dt^2} + c \frac{dx}{dt} + kx = 0 \quad \text{with trial solution } x(t) = Ae^{qt}$$

yields auxiliary equation

$$mq^2 + cq + k = 0 \quad \Rightarrow \quad q = \frac{-c \pm \sqrt{c^2 - 4mk}}{2m}$$

∃ Three possibilities:

$$\left\{ \begin{array}{ll} c^2 > 4mk & \text{overdamped} \\ c^2 = 4mk & \text{critically damped} \\ c^2 < 4mk & \text{underdamped} \end{array} \right.$$

Damped Oscillations (linear damping)

auxiliary equation:

$$q = \frac{-c \pm \sqrt{c^2 - 4mk}}{2m} = -\gamma \pm \sqrt{\gamma^2 - \omega_o^2}$$

where $\gamma \equiv \frac{c}{2m} =$ damping parameter

(note that Taylor uses β)

and $\omega_o \equiv \sqrt{\frac{k}{m}} =$ natural frequency

Damped Oscillations (linear damping)

$$c^2 < 4mk \quad (\gamma < \omega_o) \quad \text{underdamped}$$



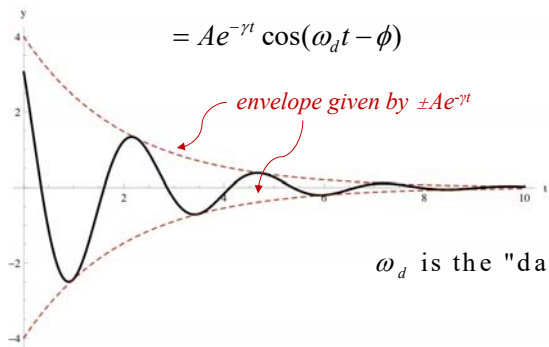
yields actual oscillations!

$$x(t) = C_+ e^{-\gamma t} e^{+i\sqrt{\omega_o^2 - \gamma^2} t} + C_- e^{-\gamma t} e^{-i\sqrt{\omega_o^2 - \gamma^2} t}$$

$$= B_1 e^{-\gamma t} \cos(\omega_d t) + B_2 e^{-\gamma t} \sin(\omega_d t) \quad \text{where}$$

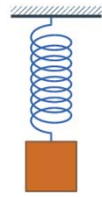
$$= A e^{-\gamma t} \cos(\omega_d t - \phi)$$

$$\left\{ \begin{array}{l} \omega_d^2 \equiv \omega_o^2 - \gamma^2 \\ \phi \equiv \tan^{-1}(B_2 / B_1) \\ A^2 \equiv B_1^2 + B_2^2 \\ C_{\pm} \equiv (B_1 \mp i B_2) / 2 \end{array} \right.$$



ω_d is the "damped frequency"

(Note Taylor uses ω_1)



$$\omega_o \equiv \sqrt{\frac{k}{m}}$$

$$\gamma \equiv \frac{c}{2m}$$